

# Estimation of physical conditions in PDRs Bayesian approach with spatial regularization



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### Aims and contributions

New large hyper-spectral surveys in radio-astronomy: game changer for study of star formation, feedback mechanisms and chemistry of interstellar gas.  $\implies$  now possible to observe full molecular clouds (10 pc size) at dense core scale (<0.1 pc) spatial resolution. For instance, the IRAM-30m Large Program «Orion B» [1] provides a 10<sup>6</sup> pixel observation map, covering  $\sim 250 \text{ pc}^2$  of the Orion B cloud with emission of dozens of molecules.

Goal To estimate maps of thermal pressure  $P_{th}$ , UV radiation intensity  $G_0$ , visual extinction  $A_V$ , scaling factor  $\kappa$  and the associated uncertainties.

**Challenge** Variability of the SNR: the brightest regions can be well constrained, but the regions with low SNR lead to degenerate solutions.

Approach  $\star$  Mixture of both additive and multiplicative noises + limited detectability  $\implies$  more realistic observation model

- $\star$  Spatial regularization  $\implies$  exploitation of the information contained in neighbouring pixels.
- $\star$  Bayesian approach  $\implies$  access to accurate credibility intervals.

# **Problem formulation**

→ Meudon PDR code [2]: solves radiative transfer, chemistry, thermal balance on stationary 1D plane-parallel model.



 $\rightarrow$  Assumption: physics in PDR = interpolation of a grid of simulations of Meudon PDR code. Defines function f s.t. for one pixel n:



### Application on toy dataset (100 pixels)



 $\rightarrow$  observation model involves detectability limit  $\omega$ , gaussian noise  $\varepsilon_{n,\ell}^{(a)}$  and lognormal noise  $\varepsilon_{n,\ell}^{(m)}$ 



defines a **likelihood** function  $\pi(y \mid x)$ .

### **Bayesian** approach

- $\rightarrow$  State-of-the-art in millimeter/IR astronomy estimations: Maximum Likelihood Estimates  $(MLE) \implies$  very sensitive to noise
- $\rightarrow$  For robust estimators: spatial regularization **prior**  $\pi(x)$  (norm of image gradient or laplacian)
- → **Posterior** probability density function:

 $\pi(x \mid y) \propto \pi(y \mid x)\pi(x)$ 

 $\rightarrow$  To derive estimators and credibility intervals from posterior distribution: sample from it with Monte Carlo Markov Chain (MCMC).

# NGC 7023 (1 pixel)



 $\rightarrow$  Our sampler mixes two kernels: one identifies local minima, one efficiently explores them.

 $\rightarrow$  Our ponctual estimator: MMSE (Mininimum) Mean Squared Error) = mean of posterior.

 $\rightarrow$  Estimation from 10 lines of CO and 2 lines of CI.

→ In contrast with [3],  $G_0$  and  $A_V$  estimated along with  $\kappa$  and  $P_{th}$ .

 $\rightarrow$  Two regions of acceptable solutions identified.

#### Summary for main mode

	MLE $[3]$	MMSE	2.5%	97.5%
$\kappa$	0.7	4.8	2.5	8.6
$P_{th} (\times 10^8)$	1	1.1	1.0	1.3
$G_0 (\times 10^3)$	2.6	1.6	1.0	2.6
$A_V$	10	3.1	1.6	30.5

### References

[1] Pety et al., The anatomy of the Orion B Giant Molecular Cloud: A local template for studies of nearby galaxies, 2016

[2] Le Petit et al., A model for atomic and molecular interstellar gas the Meudon PDR code, 2009

[3] Joblin et al., Structure of photodissociation fronts in star-forming regions revealed by Herschel observations of high-J CO emission lines, 2018

# Conclusions

### Achieved:

- $\checkmark$  Spatial regularization  $\implies$  more robust estimations of maps of parameters,
- $\checkmark$  Bayesian approach  $\implies$  more complete description than ponctual estimators.

### **Future Work:**

- $\rightarrow$  Application to other environments than PDR (shocks, dark clouds, etc.),
- $\rightarrow$  Code acceleration to scale to ~ 10<sup>6</sup> pixel observations (e.g., Orion B IRAM Large Programm).